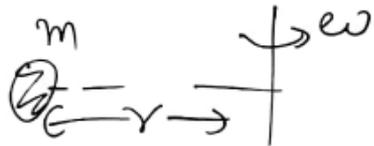


# Rotational Motion

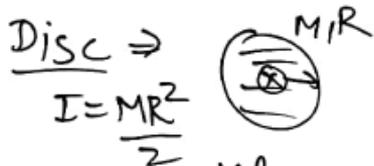
## # Moment of inertia $\Rightarrow$



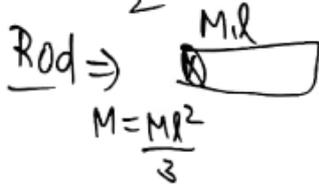
$$I = mr^2$$



$$I = MR^2$$



$$I = \frac{MR^2}{2}$$

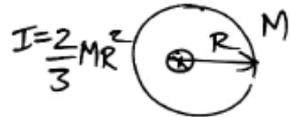


$$I = \frac{Ml^2}{3}$$



$$I = \frac{Ml^2}{12}$$

Hollow sphere  $\Rightarrow$



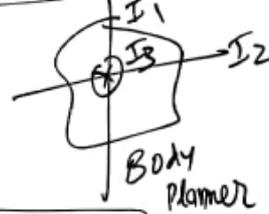
$$I = \frac{2}{3}MR^2$$

Solid sphere  $\Rightarrow$



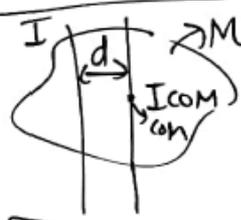
$$I = \frac{2}{5}MR^2$$

## Per axis theorem



$$I_3 = I_1 + I_2$$

## Parallel axis theorem



$$I = I_{com} + Md^2$$

Torque  $\Rightarrow$

\*  $\vec{\tau} = \vec{r} \times \vec{F}$  dir  $\Rightarrow$  right hand rule  
 $|\tau| = rF \sin \theta = r_{\perp} F = rF_{\perp}$   $\Rightarrow$   $\tau = \tau_z$

\*  $\tau_{axis} = (\vec{r} \times \vec{F})$  component along the axis of rotation

\* Eq<sup>m</sup>  $\Rightarrow$   $\vec{F}_{net} = 0$  &  $\vec{\tau}_{net} = 0$

#  $\tau = I\alpha$

## # Angular Momentum $\Rightarrow$

$$\vec{L} = m(\vec{r} \times \vec{v})$$

$$\vec{L} = I\omega$$

#  $\tau_{net} = 0 \Rightarrow \vec{L}_i = \vec{L}_f$  conservation of angular momentum.

Angular impulse  $\Rightarrow$

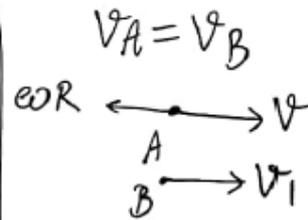
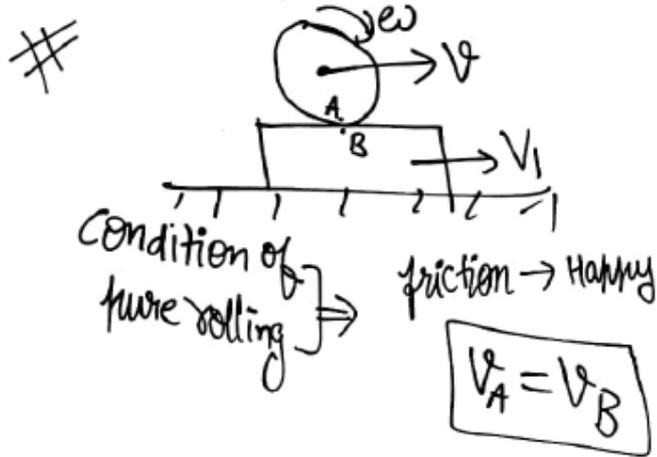
$$\int \tau dt = L_f - L_i$$

# Rotational Motion

# Pure Rolling  $\Rightarrow$

Static Friction  $\rightarrow$  Khush

$\rightarrow$  When two surfaces which are in contact stays in contact.



$$v_A = v_B$$

$v - \omega R = v_1$

Condition for pure rolling.

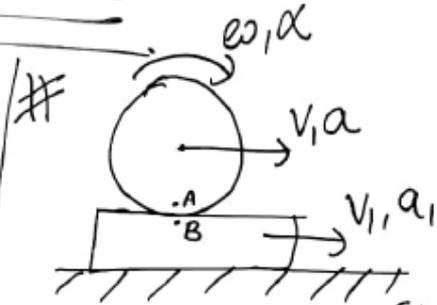
# if surface (Platform) is fixed.

$$v_1 = 0$$

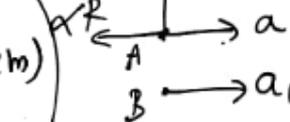
$$v - \omega R = 0$$

$$\begin{aligned} v &= \omega R \\ \omega &= \frac{v}{R} \end{aligned}$$

Condition of pure rolling for fixed surface



Condition for pure rolling  $\Rightarrow$  friction happy. along the contact surface



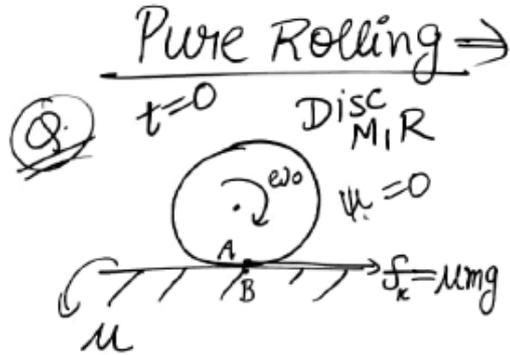
$a - \alpha R = a_1$

# if the surface is fixed  $\Rightarrow a_1 = 0$

$$\begin{aligned} a &= \alpha R \\ \alpha &= \frac{a}{R} \end{aligned}$$

Condition for pure rolling for fixed surface

# Rotational Motion



After time  $t$  pure rolling start. Find  $v$  &  $\omega$  when it happens?

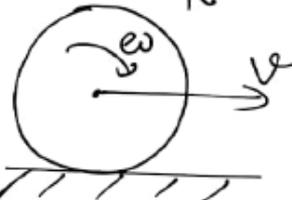
Soln  $\Rightarrow f = \mu mg$

Method-1  $\Rightarrow a = \mu g$

$\tau = 0 \Rightarrow \tau = I \alpha$

$\mu mg R = \frac{MR^2}{2} \alpha \Rightarrow \alpha = \frac{2\mu g}{R}$

$t=t$  pure rolling  $\Rightarrow \omega = \frac{v}{R}$



Translation eq<sup>n</sup>  $\Rightarrow$

$v = u + at$

$v = \mu g t \Rightarrow t = \frac{v}{\mu g}$  (1)

Rotational eq<sup>n</sup>  $\Rightarrow$

$\omega = \omega_0 + \alpha t$

$\omega = \omega_0 - \frac{2\mu g t}{R}$  (2)

$\omega = \frac{v}{R}$  &  $t = \frac{v}{\mu g}$  put in (2)

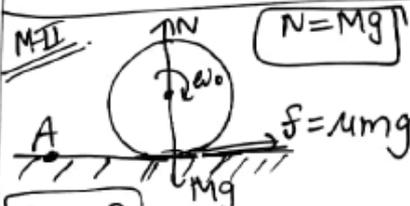
$\frac{v}{R} = \omega_0 - \frac{2\mu g v}{R \mu g}$

$\frac{3v}{R} = \omega_0$

$v = \frac{\omega_0 R}{3}$  m/s

$\omega = \frac{v}{R} \Rightarrow \omega = \frac{\omega_0}{3}$  rad/s

M.F.I.



$Z_A = 0 \Rightarrow$  Angular Momentum conserved.

$L_i = L_f \Rightarrow$

$L_i = L_f$  about A

$\frac{MR^2 \omega_0}{2} = \frac{MR^2 \omega}{2} + MRv$  (1)

pure rolling  $\Rightarrow \omega = \frac{v}{R}$  put in (1)

$\frac{MR^2 \omega_0}{2} = \frac{MR^2 v}{2R} + MRv$

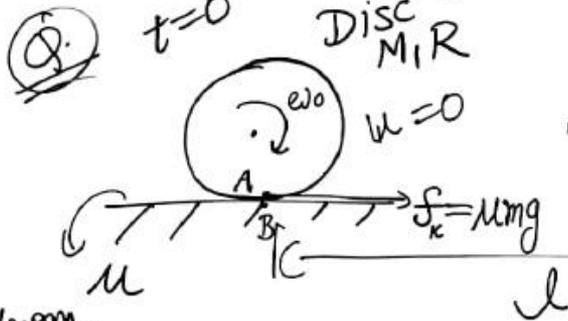
$\frac{\omega_0 R}{2} = \frac{3v}{2}$

$v = \frac{\omega_0 R}{3}$

$\omega = \frac{v}{R} \Rightarrow \omega = \frac{\omega_0}{3}$

# Rotational Motion

Pure Rolling  $\Rightarrow$



from  $t=0 \rightarrow t = \frac{\omega_0 R}{3\mu g}$

Find work done by friction?

Soln  $\Rightarrow$   $W \cdot D_f = K_f - K_i$

$$K_i = \frac{1}{2} I \omega^2 = \frac{1}{2} \frac{MR^2}{2} \omega_0^2 = \frac{MR^2 \omega_0^2}{4}$$

$$K_f = \frac{1}{2} Mv^2 + \frac{1}{2} I \omega^2 = \frac{1}{2} M \frac{\omega_0^2 R^2}{9} + \frac{1}{2} \frac{MR^2}{2} \frac{\omega_0^2}{9} = \frac{MR^2 \omega_0^2}{12}$$

K.E. ↓

$t=t$   $\omega = \frac{v}{R}$   
 Pure Rolling



$v = \frac{\omega_0 R}{3}$ ,  $\omega = \frac{\omega_0}{3}$   
 $t = \frac{v}{\mu g} = \frac{\omega_0 R}{3\mu g}$

$W \cdot D_f = K_f - K_i$   
 $\frac{MR^2 \omega_0^2}{12} - \frac{MR^2 \omega_0^2}{4}$

$W \cdot D_f = -\frac{MR^2 \omega_0^2}{6}$

M-II Translation work done

$W \cdot D_f = f \cdot l$

$v^2 - u^2 = 2as$

$\frac{\omega_0^2 R^2}{9} - 0 = 2\mu g l$

$l = \frac{\omega_0^2 R^2}{18\mu g}$

$W \cdot D_f = \mu mg \cdot \frac{\omega_0^2 R^2}{18\mu g}$

Translational

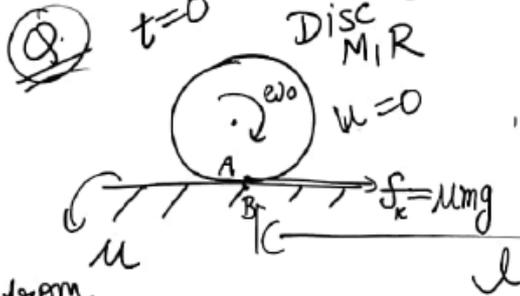
$W \cdot D_f = \frac{M \omega_0^2 R^2}{18}$

Rotational work done

$W \cdot D = \int \tau \cdot d\theta$

# Rotational Motion

## Pure Rolling $\Rightarrow$



from  $t=0 \rightarrow t = \frac{\omega_0 R}{3\mu g}$

Find work done by friction?

Soln  $\Rightarrow$   $W \cdot D_f = K_f - K_i \Rightarrow W \cdot D_f = -\frac{MR^2 \omega_0^2}{6}$

M-II Rotational  $W \cdot D = \int \tau \cdot d\theta$

$W \cdot D = \tau \theta \cos 180^\circ = -\tau \theta$

$W \cdot D = -MmgR\theta = -MmgR \frac{2\omega_0^2 R}{9\mu g}$

$W \cdot D_R = -\frac{2}{9} M\omega_0^2 R^2$



$v = \frac{\omega_0 R}{3}, \omega = \frac{\omega_0}{3}$

$t = \frac{v}{\mu g} = \frac{\omega_0 R}{3\mu g}$

$\omega^2 = \omega_0^2 + 2\alpha\theta$

$\frac{\omega_0^2}{9} - \omega_0^2 = 2\alpha\theta$

$-\frac{8}{9}\omega_0^2 = -\frac{4\mu g}{R}\theta$

$\theta = \frac{2\omega_0^2 R}{9\mu g}$

M-II Translation work

$W \cdot D_f = f \cdot l$

$v^2 - u^2 = 2as$

$\frac{\omega_0^2 R^2}{9} - 0 = 2\mu g l$

$l = \frac{\omega_0^2 R^2}{18\mu g}$

$W \cdot D_f = Mmg \cdot \frac{\omega_0^2 R^2}{18\mu g}$

Translational

$W \cdot D_t = \frac{M\omega_0^2 R^2}{18}$

Rotational work done

$W \cdot D = \int \tau \cdot d\theta$

Total work done by friction  $\Rightarrow$

$W \cdot D_f = W \cdot D_R + W \cdot D_t$

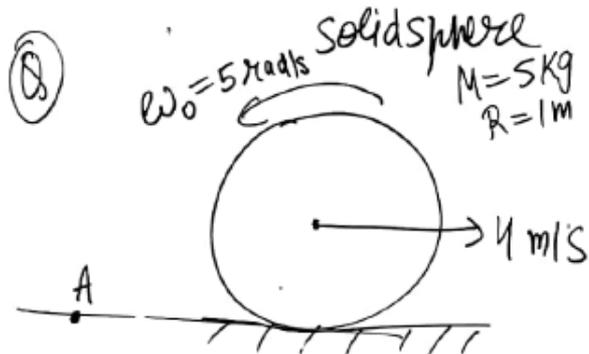
$= -\frac{2}{9} M\omega_0^2 R^2 + \frac{M\omega_0^2 R^2}{18}$

$= M\omega_0^2 R^2 \left[ \frac{-4+1}{18} \right]$

$= M\omega_0^2 R^2 \left[ \frac{-3}{18} \right]$

$W \cdot D_f = -\frac{M\omega_0^2 R^2}{6}$

## Rotational Motion



(a) Find  $\omega$  &  $v$  when pure rolling starts?

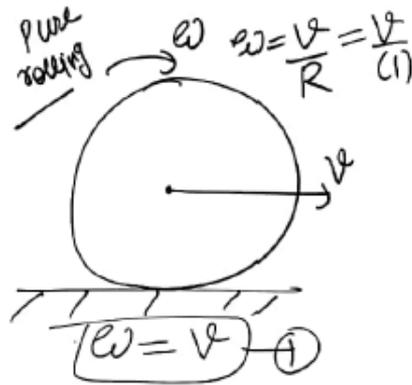
(b) Find work done by friction?

Sol<sup>n</sup>  $\Rightarrow \tau_A = 0 \Rightarrow L_i = L_f$

$$I = \frac{2}{5} MR^2 = \frac{2}{5} (5)(1)^2 = 2$$

$$L_i = 2(5) - 5(1)(4) = -10$$

$$L_f = -2\omega - 5(v)$$



$$-2\omega - 5v = -10$$

$$-7\omega = -10$$

$$\omega = \frac{10}{7} \text{ rad/s}$$

$$v = \frac{10}{7} \text{ m/s}$$

$$W \cdot D_f = K_f - K_i$$

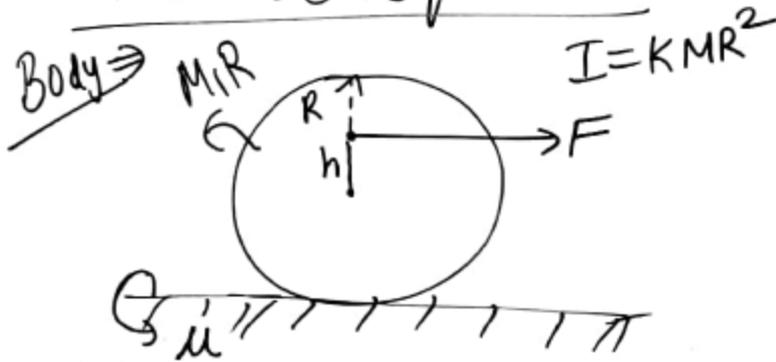
$$K_i = \frac{1}{2}(5)(4)^2 + \frac{1}{2}(2)(5)^2$$

$$K_f = \frac{1}{2}(5)\left(\frac{10}{7}\right)^2 + \frac{1}{2}(2)\left(\frac{10}{7}\right)^2$$

$$W \cdot D_f = K_f - K_i \quad \checkmark$$

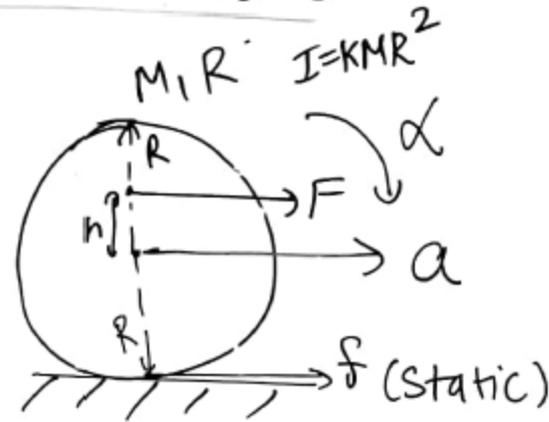
# Rotational Motion

## Force Equation $\Rightarrow$



# if  $\mu = 0$   $F = Ma$  |  $\tau = I\alpha$   
 $a = \frac{F}{M}$  |  $\alpha = \frac{hF}{I}$

# when friction is present & sufficient for pure rolling  $\Rightarrow$  if  $\alpha \neq \frac{a}{R}$  then friction tries to make  $\alpha = \frac{a}{R}$  (pure rolling)



pure rolling  $\Rightarrow \alpha = \frac{a}{R}$  — (1)

(1)  $F_{net} = Ma$

$F + f = Ma$  — (2)

(2)  $\tau = I\alpha$  (COM)

$-Fh + fR = -KMR^2\alpha$  — (3)

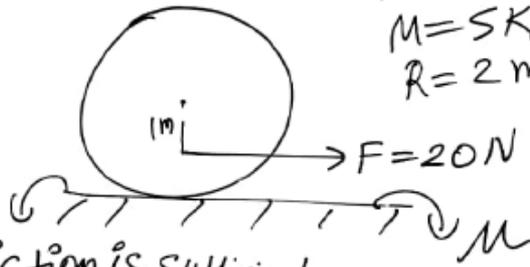
## Rotational Motion

Q

Solid sphere

$$M = 5 \text{ kg}$$

$$R = 2 \text{ m}$$

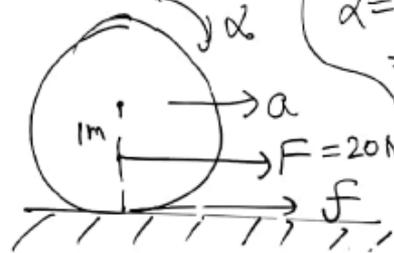


friction is sufficient for pure rolling

(a) Find  $f$ ,  $\alpha$ ,  $a$  when pure rolling starts?

Solid sphere  $I = \frac{2}{5} MR^2$

$$= \frac{2(5)(2)^2}{8} = 8$$



$$\alpha = \frac{a}{R} = \frac{10}{2 \cdot 7} = \frac{10}{14}$$

① Pure rolling  $\Rightarrow \alpha = \frac{a}{R}$

$$\alpha = \frac{a}{2} \quad \text{--- (1)}$$

②  $F_{net} = Ma \Rightarrow 20 + f = 5a$  --- (2)

③  $\tau_{COM} = I_{COM} \alpha \Rightarrow 20(1) + f(2) = 8\alpha$  --- (3)

$$20 + 2f = 4a \quad \text{--- (4)}$$

②  $\times 2$  - (4)  $\Rightarrow 40 + 2f = 10a$

$$\begin{array}{r} 40 + 2f = 10a \\ -20 + 2f = 4a \\ \hline 20 = 6a \Rightarrow a = \frac{10}{3} \text{ m/s}^2 \end{array}$$

$$20 = 6a \Rightarrow a = \frac{10}{3} \text{ m/s}^2$$

(b) Find the minimum value of  $\mu$  required for pure rolling?

$$f \leq f_{max}$$

$$\frac{90}{7} \leq \mu mg$$

$$\frac{90}{7} \leq \mu 50$$

$$\mu \geq \frac{9}{35}$$

$$\mu_{min} = \frac{9}{35} \Rightarrow \text{for pure rolling}$$

$$\mu < \frac{9}{35} \Rightarrow \text{then no rolling slipping occurs}$$